

Analysis III for Engineering Students

Work sheet 3

Exercise 1:

Compute the Jacobian matrices for the following functions

- a) (i) $\hat{\mathbf{f}}_1 : \mathbb{R}^2 \rightarrow \mathbb{R}^3$, $\hat{\mathbf{f}}\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2x + 3y \\ x^2 + y^2 \\ xy \end{pmatrix}$.
- (ii) $\mathbf{f} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$, $\mathbf{f}\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} e^{(3\gamma+1)x_1} - x_2 - 1 \\ 5x_1 + e^{(3\gamma-1)x_2} - 1 \end{pmatrix}, \quad \gamma \in \mathbb{R}$ fixed parameter.
- (iii) $\tilde{\mathbf{f}} : \mathbb{R}^3 \rightarrow \mathbb{R}^3$, $\tilde{\mathbf{f}}\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} -4x_1 + x_2^2 - 3x_3 \\ x_1^2 - 3x_2 + x_3^2 \\ 2x_1 - 4x_2^4 + x_3 \end{pmatrix}$.

- b) For the transformation from spherical coordinates to Cartesian coordinates

$$\mathbf{g} : \mathbb{R} \times [0, 2\pi] \times [-\frac{\pi}{2}, \frac{\pi}{2}] \rightarrow \mathbb{R}^3, \quad \mathbf{g}\begin{pmatrix} r \\ \phi \\ \theta \end{pmatrix} = \begin{pmatrix} r \cos(\phi) \cos(\theta) \\ r \sin(\phi) \cos(\theta) \\ r \sin(\theta) \end{pmatrix}$$

it holds that

$$\det(\mathbf{J} \mathbf{g}(r, \phi, \theta)) = r^2 \cos(\theta).$$

Provide the determinant of the Jacobian matrix for the transformation to elliptic coordinate system

$$\tilde{\mathbf{g}} : \mathbb{R} \times [0, 2\pi] \times [-\frac{\pi}{2}, \frac{\pi}{2}] \rightarrow \mathbb{R}^3, \quad \mathbf{g}\begin{pmatrix} r \\ \phi \\ \theta \end{pmatrix} = \begin{pmatrix} ar \cos(\phi) \cos(\theta) \\ br \sin(\phi) \cos(\theta) \\ cr \sin(\theta) \end{pmatrix}$$

for fixed values of a, b, c .

Exercise 2:

Compute the 2-nd order Taylor polynomial of

$$f(x, y, z) = 2 + xz + y^2 + e^x y^2 \cos(z)$$

around a point $(x_0, y_0, z_0)^T := (0, 1, \pi)^T$.

Classes: 15.–19.11.21